Bathless Dissolution: Validation of System Performance

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ith FDA's growing emphasis on the need to establish that systems are suitable for their intended uses, pharmaceutical companies are increasingly demanding that their vendors provide them with an ever-expanding level of proof of performance. In the laboratory area, some companies have gone so far as to demand that equipment suppliers provide complete validation protocols



For many years the USP paddle method has proved to be a robust test for determining the dissolution rates of solid dosage forms. This article focuses on validating the performance of a new, innovative bathless dissolution system.

encompassing the system installation, operation, and, in some cases, performance qualification. Most vendors, understanding that FDA holds the end user responsible for on-site validation, have tended to limit their support to providing guidance validation protocols as a line item option available to the user. Typically, vendors will also charge for additional support in developing the end user's validation protocol. In some cases, when the user has purchased direct vendor validation support, vendors have provided their personnel to perform the user's approved validation protocol, with the user's quality unit acting as the review and approval agent.

This article discusses the verification of system compo-

nent conformity to specifications as well as key highlights from the validation of the performance of the Premiere 5100 bathless dissolution system (Distek, Inc., North Brunswick, NJ). These studies were performed to establish that the system is fit for use in performing the United States Pharmacopeia (USP) suitability test (1) specifically and for USP-based dissolution studies in general. The system is a seven-vessel, directly heated unit fitted with paddles. Before these studies began, the system was installed and its installation and operation were verified as conforming to the manufacturer's specifications. All measurements were made using calibrated NIST-traceable measurement instruments, except that vessel hemisphericity was verified using VesselChek, an external metal template (Distek). The system's level was confirmed using the built-in circular spirit level and an auxiliary carpenter's level. The system was installed on a bench in the firm's demonstration room with a printer attached to record sets of time, temperature, and stirring speed (rpm) data. The nominal temperature in this area was approximately 22°C. In keeping with vendor recommendations, the system was not placed in the discharge stream of any heating, ventilation, and air conditioning (HVAC) register.

The general approach to validate system performance was to:

• verify the physical dimensions of the key components (vessels, paddles, and vessel covers)

• establish that the installed components met their alignment and, in the case of the paddles, their rotational specifications

• confirm the accuracy of the system's reference temperature probe on which the seven temperature-sensing shafts' accuracy is based and perform a calibration check on the system

• determine that the system's heating met its heating time windows

• establish that the temperature of the medium in the vessels conformed to its set point; was uniform within the stirred medium; met its expected between- and withinvessel temperature variation tolerances; remained within its short- and long-term drift specifications; and was not significantly affected when, contrary to USP's directions, the covers were removed from the vessels.

In all cases, the plan was to establish that the results obtained conformed to Distek's established specifications (see Tables I and II).

THE VALIDATION PLAN

Based on the general approach outlined in the preceding paragraph, a formal validation plan was drafted. After



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Item	USP Requirements	Vendor Requirements		
Vessel Specifications				
Material of construction	Glass or other transparent material that is nonreactive	Borosilicate glass		
Key markings	Not specified	Serial number, volume lines, and a locating mark on its outer surface		
Vessel shape	Top-flanged cylinder with a hemispherical bottom	Top-flanged (with flat flange underside cylinder with a hemispherical bottom		
1-L vessel's outside height	160-210 mm	164.0-172.0 mm		
1-L vessel's outside diameter (o.d.)	Not specified	105.0-109.0 mm		
1-L vessel's inside diameter (i.d.)	98-106 mm	99.0-104.0 mm		
1-L vessel's wall thickness	Not specified	2.3-3.7 mm		
1-L flange o.d.	Not specified	130.0-136.0 mm		
Paddle Specifications				
Material of construction	Shaft and blade are 303 (or equivalent) stainless steel (SS) with bottom of blade flush with shaft	Machined 316 SS hollow shaft with an embedded temperature sensor. 316 SS threaded blade sealed by a Viton 0 ring		
Identification	Not specified	Serialized		
Shape of paddle and shaft	As specified in Figure 2 of USP General Chapter <711>, Dissolution	Conforms to USP		
Shaft length (without paddle)	Not specified	454.0-464.0 mm		
Shaft o.d.	9.4-10.1 mm	9.47-9.55 mm		
Blade height	18.5-19.5 mm	18.6-19.4 mm		
Blade thickness	3.0-5.0 mm	3.2-4.8 mm		
Upper blade width	74.0-75.0 mm	74.0-75.0 mm		
Tip's radius of curvature	1.2 mm (±1.0 mm)	1.2 mm (-0.2 mm to +0.8 mm)		
Blade's width at bottom	42.0 mm (±1.0 mm)	42.0 mm (±0.9 mm)		
Blade's radius of curvature (when measured from center of shaft 35.8 mm from the blade's bottom)	41.5 mm (±1.0 mm)	41.5 mm (±0.9 mm)		
Vessel Covers				
Material of construction	Not specified	Acrylic halves joined with acetel hinge		
Design	Fitted cover with openings for thermometer and specimen withdrawal	Hinged, fitted cover with one capped opening on each half for sampling		
o.d. and thickness	Not specified	18.0-124.0 mm (o.d.) 11.0-15.0 mm (thickness)		

Table I: USP's and Distek's specifications for key physical components.

receipt of corporate approval, the activities outlined in the protocol began. As the studies progressed, the details of the plan were updated to incorporate changes arising from experimental findings, scheduling, and priority conflicts. The approved plan required that, at a minimum, the critical components be determined to meet the USP tolerances before any system performance studies would be initiated. In addition, before any operational studies were to be conducted, the plan required that physical and position measurements of the sys-

tem's key components be determined to meet the manufacturer's specifications and that the temperature accuracies of the system's reference probe and the seven temperature-sensing shafts be shown to be accurate in comparison with an appropriate NIST-traceable external temperature-measuring system.

The plan called for first sequentially determining room temperature, vessel dimensions, shaft and paddle dimensions, vessel cover dimensions, and the system's calibration probe (Cal. Probe) temperature reference unit's conformity to a NIST-traceable, calibrated TempChek temperaturemeasurement system (Distek).

Then, the seven shafts were to be calibrated, the vessels installed, the paddle heights set, and the paddle centering, clearance, wobble, and rise determined. Next, the paddles' rotations were to be determined to conform to USP specifications as well as to the manufacturer's tighter acceptance criteria using an RPM-Chek, a NIST-traceable, high-resolution (0.1 - rpm)tachometer (Distek). The next step was to study the heating of

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Table I	: 0	perational	performance	targets	and	tolerances.
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Item	USP Targets and Tolerances	Vendor Targets and Tolerances		
Main unit vessel support plate's level	Implicitly level	Bubble on standard 25-mm or larger diameter bubble level must be within the level's centering circle		
Shaft runout	Not specified	≤0.26 mm		
Installed blade runout	≤0.5 mm	≤0.5 mm		
Installed shaft deviation from vessel center line (centering)	≤2.0 mm	≤2.0 mm		
Clearance between bottom of installed paddle blade and the inside bottom of its vessel (paddle not rotating)	23.0-27.0 mm	23.0-27.0 mm		
Maximum upward displacement of paddle when shaft is rotating	≤0.5 mm	≤ 0.5 mm		
Rotational speed control accuracy	$\pm4\%$ of target for 25-250 rpm	\pm 1% of target for 25-49 rpm \pm 0.5% of target for 50-150 rpm \pm 0.3% of target for 151-250 rpm		
Operating clearance between drive unit and top of vessels when operating (important for sampling access)	Not specified	At least 190.0 mm		
Temperature of dissolution medium when set at 37.0 °C	36.5-37.5 °C	36.65-37.35 °C		
Temperature difference between medium in different vessels (vessels at 37 °C)	Not specified	≤0.4 °C (paddles at 25-250 rpm)		
Temperature homogeneity within a filled 1-L vessel (1 L of water and top, middle, bottom, and shaft sensors used to determine this)	Not specified	≤0.3 °C (paddles at 25-250 rpm)		
Time to heat 1 L of water from the lab's ambient temperature (≥20 °C) to 37 °C within USP limits	Not specified	≤21 min (paddles at 25 rpm)≤12 min (paddles at 250 rpm)		
Short-term (15-min) drift in temperature (set = 37 °C)	Not specified	≤0.25 °C (paddles at 25-250 rpm)		
Long-term (24-h) drift in temperature (set = 37 °C)	Not specified	≤0.35 °C (paddles at 25-250 rpm)		

1-L aliquots of water to 37°C as well as temperature stabilization while stirring at the limits (25 rpm and 250 rpm). The purpose of this step was to verify that the system met its initial heating and temperature stabilization requirements. When the preceding studies were successfully completed, tests were to be conducted addressing temperature gradient (top, middle, and bottom) and temperature fluctuation. The effect on temperature stability and set point of removing the vessel covers was also to be studied.

To complete the validation, short-term (15-min) and longterm (24-h) temperature and rpm conformity studies were to be conducted with the paddles rotating at 250 rpm. Following completion of the initial studies, the analysts decided to add a short-term (15-min) and longterm (24-h) temperature and rpm conformity study with the paddles rotating at 25 rpm. This was done to establish the effect of low-speed stirring on the temperature conformity of the vessel's contents to set point.

EXPERIMENTS, RESULTS, AND FINDINGS

The vessels to be used were identified and their suitability verified by measuring key dimensions. Their bottom hemisphericity was confirmed using the manufacturer's standard template. Next, the vessel covers' dimensions were confirmed to meet the manufacturer's specifications. Following this, the paddle shafts and their position in the system were identified and the shafts' diameters and certain key paddle dimensions were measured. In addition, suitable standard metal templates were used to confirm the radius of curvature of the blades and the blade tips.

Following the verification of the physical dimensions of the vessels, paddles, and vessel covers, the vessels were installed in their designated locations and

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the clearance of the paddles from the vessel bottoms was set. Next, the centering of the shafts in the vessels and the clearance between each paddle and the drive head were measured and found to meet specifications. Paddle centering and clearance were checked periodically to confirm conformance to specifications throughout the study.

In conjunction with per-

forming the required physical measurements, the accuracy of the system's calibration probe was confirmed to give temperature values accurate within 0.03°C in the interval from 22°C to 40°C. The differences observed between the calibration probe and the calibrated, NIST-traceable unit were +0.03°C at 22.2°C and -0.01°C at 40.0°C. (The NIST-traceable unit's accuracy is such that its values are accurate to within ± 0.02 °C in the range between 20 and 50 °C). The calibration probe was then used to perform a two-point calibration (at ~20 °C and ~37 °C) of the seven temperature-sensing shafts using vessels filled with water stirred at 150 rpm per the manufacturer's current calibration procedure. In addition, the proper operation of the safety interlock that disables rotation

Notes

1. In water bath-based systems, a major factor that limits the heating of the vessel's contents is the limited temperature gradient between the medium in the vessel and the water bath. The initial difference is typically on the order of 15°C. In contrast, whereas the initial temperature gradient between the direct-heating jacket and its vessel is typically only a few degrees, this system is capable of rapidly increasing the jacket's temperature to the point that maximum gradient can be more than five times that generated by the water bath. Moreover, as the vessel's contents begin to warm, the system's controllers adjust the heat input based on the temperatures being fed back from the shaft probes.

2. When the medium is heated to its target temperature, stirring should be as rapid as possible to the point that air starts becoming entrained in the medium or, in cases in which the medium contains certain surfactants, the medium begins to foam. For water, ≥0.1 N aqueous hydrochloric acid, simulated gastric fluid without enzymes, and simulated intestinal fluid without enzymes, 150 rpm is a good compromise value. If the analyst is concerned about resaturating the medium with air before the start of the test period, he or she should consider using systems that dispense deaerated medium at the test temperature into the vessels. This is true because the medium, if in contact with air, rapidly equilibrates to saturation during any period of stirring and heating. This is the case partly because the solubility of air in the medium decreases as the medium is heated. In addition, the time to reach temperature equilibrium, even in an actively heated system such as the one used here, is at least 15 min. Water bath-based systems typically require more than twice as long. Consequently, the medium will be close to saturation at the beginning of a valid test unless the medium has been degassed and preheated to the required temperature and is maintained in this state until just before dispensing.

3. In actuality, the time for the system to equilibrate to a given temperature is a complex function of the initial fill volume (typically 500-1000 mL in a standard USP 1-L vessel), the initial fill volume's temperature, the stirring rate, and the system's set point. On the lower end, the set point is limited to the greater of 20° C or ambient +5.0°C and, because of the system's design, to 45° C on the upper end.

3.1 As a general rule of thumb, the closer the temperature of the fill is to the set point, the shorter is the time required to equilibrate the contents to the set point temperature. It is important to prevent the heating process from raising the medium's temperature significantly above the set point because dissolution systems are not, because of cost and reliability considerations, designed to provide active cooling.

3.2 Up to a point (see Note 2), increasing the stirring speed (rpm) during the heat-up period will reduce the equilibration time.

3.3 Because the vessel jackets actually contain a lower heater designed to heat the region from the jacket's bottom to just below the 500-mL level and an upper heater to heat the region from 500 mL to just below 900 mL, the system uses the fill level to limit the heaters used in heat-up. To minimize the risk of damage to the vessels and the heater jackets, the system uses only the lower heater for fills up to 500 mL. Both heaters are used for volumes between 500 mL and 1000 mL.

3.4 Based on the initial fill's temperature, the system also selects an initial heating rate to minimize the risk of overheating the medium and periodically updates that rate based on the temperature measurements fed back by the shafts' sensors.

4. Should one wish to place a suitable small-thermal-mass, rapid-response temperature probe at a top position that is not biased by heat transfer effects occurring at the vessel's surface, it is recommended that it be placed so that its active region is just below the 900-mL level for a 1-L fill, just at the 800-mL level for a 900-mL fill, or just at the 650mL level for a 750-mL fill. For 500-mL studies, it is recommended that a suitable probe be positioned at the top and bottom because the region of the probe that must be immersed for an accurate reading remains unchanged. The two recommended levels are at 350-400 mL for the upper position and at 150-200 mL for the lower position.

5. It is recommended that the system be installed in areas of low airflow. If it is installed where there is a significant airflow across the unit, such as near an HVAC register, then the unit should be shielded from this draft in order to operate within its design specifications. Although this is always an important issue, it is especially true for the user who chooses to operate the system without the covers installed.



when the drive head is fully raised was also confirmed.

After centering and clearance verification, the shaft rpm, shaft wobble (at just above the blade), and paddle lift were measured and found to meet specifications. At this point, the experiments had established that the system was suitable for studying various aspects of the system's temperature performance. Vessel fill volume was fixed at 1 L. Because the goal was to establish that the system performs within its stated temperature tolerances across the entire range of controlled stirring speeds, the temperature studies were performed at the lowest (25 rpm) and at the highest (250 rpm) stirring speed in the manufacturer's specified control range.

Though a variety of studies were performed, this article will present only the key results obtained. The bathless system uses heater jackets to directly heat and maintain the vessel's contents at a given temperature. Because each temperature-sensing stirring shaft is used to monitor temperature and to provide feedback to the vessel's heater-control circuitry, the medium's heating and temperature control are the crucial aspects of this system's performance that must be established.

The experiments discussed below are:

initial heating

• divergence of the equilibrium temperature from the set point

• temperature uniformity within the medium in the vessel

• long-term limiting temperatures about the set point Table III: Study schedule for initial heating and stabilization.

Day	Stirring Speed (rpm)	Water Start Temperature (8C)	Analyst Number	Results Presented in Trial #	Remarks
1	25	21.5	1	B1	
	250	21.7	1	A1	
2 25 250	25	24.6	1	D1	
	250	22.9	1	C1	
3	25	21.5	2	B2	Repeat of Day 1
	250	20.1	2	E1	

Table IV: Initial medium heating and medium stabilization studies.

Trial ID*	Pac	Idles at 250 rp	m	Padd			
	Time (min) and Temperature (°C)			Time (min) and Temperature (°C)			
	A1	C1	E1	B1	D1	B2	
Start	0 21.7	0 22.9	0 20.1	0 21.5	0 24.6	0 21.5	
Met USP	12 36.9	9 37.1	12 36.9	18 37.1	12 37.4	15 37.0	
Met Distek	12 36.9	9 37.1	12 36.9	21 36.9	18 36.9	17 36.9	
Equilibrium	19 36.95	17 36.96	19 36.93	25 36.94	25 36.98	23 36.9	
Temp.	Avg.	36.95		Avg.	36.95		

• the effect on the equilibrium set point when the vessel's covers are removed.

INITIAL HEATING

By not stating the initial temperature of the medium being dispensed, USP 23's General Chapter <711>, Dissolution, expects that the initial temperature of the medium being dispensed will be ~25°C (USP 23, General Notices, p. 9). Therefore, the analyst is expected to dispense the appropriate volume of lab-temperature medium, cover the vessels to minimize evaporative losses that could affect result accuracy, and heat the vessel's contents to 37.0°C while stirring. Accordingly, a series of experiments was performed in which 1 L of water, at temperatures between 20°C and 25°C, was placed in each of the vessels and allowed to equilibrate briefly. Then heating was initi-

ated and system performance monitored. The stirring rate was varied because, outside of initial medium temperature and volume of fill, it has a significant effect on the time required for the system to stabilize within USP's allowed temperature range (36.5-37.5°C). One-liter volumes were selected because they represent the vessel's maximum fill. Table III presents the experimental set that resulted, and Table IV summarizes the results. As the data clearly show, the stirring rate has a major effect on equilibration time both with respect to meeting USP's allowed range and to reaching a steady state. The 250-rpm tests showed that, depending on the initial temperature of the water used, it took from 9 to 12 min to reach USP's range, whereas at 25 rpm it took 12-18 min.

Further, though the times to reach near-steady-state temper-



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atures varied from 11 to 12 min at 250 rpm, the corresponding times at 25 rpm were from 17 to 21 min. In addition, the data also indicated that the control band (the range of temperatures about the average values), though small (<0.1°C), was at least 50% wider when the stirring rate was 25 rpm than it was when the stirring rate was 250 rpm. These findings indicate that it is best to keep the initial temperature of the bulk medium as near 25°C as is feasible to minimize heat-up times. By comparison, the times to heat the contents of a borosilicate-glass vessel under the same conditions using typical water bath-based systems are more than twice the times reported here (see also sidebar, Notes 1-4).

Finally, as a result of the algorithms used in the system's software and the hardware design, the equilibrium temperatures observed for a 37.0°C set point converged on ~36.95 \pm 0.03°C in all six trials (see Table IV).

DIVERGENCE OF THE EQUILIBRIUM TEMPERATURE FROM THE SET POINT

A fundamental problem facing the designers of near-roomtemperature temperaturecontrol systems that provide active heating but rely on ambient air for cooling is that temperature overshoot must be minimized because ambient air is a poor coolant. This is one reason that the designers of such systems typically specify the system's lower control limit as ambient plus 5°C. The dissolution system described in this article belongs to this class of

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temperature-control systems.

As the preceding and the following data indicate, though the system's set point was 37.0°C, the temperatures reported by the shafts' calibrated probes, accurate to within 0.02°C, apparently converged to 36.95°C. Considering the fact that, to minimize customer cost, this system has no active cooling components, this small divergence is within the ±0.1°C design tolerance allowed. Moreover, this result is well within the set point control tolerance required by USP (±0.5°C) and the manufacturer's tighter ±0.35°C tolerance.

TEMPERATURE UNIFORMITY OF THE MEDIUM IN THE VESSEL

Vessel temperature uniformity is one of the areas that must be addressed in the performance validation of any dissolution system. USP does not address this issue, and the authors found no published factual information in this area. As before, studies were conducted at the limits of the stirrer's controlled operating range both to cover the system's controlled stirring range and to provide the maximum difference so that experiments would have the best chance of identifying and estimating even a small stirrerrpm effect that otherwise might be buried in the noise.

After several preliminary studies, definitive studies were carried out (see Table V) using an accurate (±0.02°C in the region from 20 to 50°C), calibrated, small-volume, smallthermal-mass temperature probe and measurement system to study the temperature in each vessel at the 900-mL, 500mL, and bottom levels in the vessel. The probe was inserted through the vessel's cover and positioned. Then, at approximately 2-min intervals, triplicate readings were taken at each level and recorded. Only the last two readings were used in the determination of local temperature and temperature variability. The data from these two studies indicated the presence of small temperature gradients within the vessel.

Moreover, as expected, the temperature gradient formed when the 1-L water aliquots were stirred at 25 rpm was more noticeable and slightly larger than the gradient formed when the water was stirred at 250 rpm. Although the gradient between the bottom and the 500-mL level was buried in the experimental noise at 250 rpm (but was estimated at ±0.05°C), its magnitude had increased to the point that it was approximately the same level as the system's apparent between-vessel variability in the 25-rpm test. However, all measured values in the region between the bottom and the 500mL level were within the manufacturer's specifications. Even at 25 rpm, the divergences between the 500-mL level and the bottom were within 0.2°C of the system's set point. Based on the findings from these studies, the uniformity of the zone from the middle of the vessel downward, where most of the initial dosage unit disintegration and initial dissolution take place, was established to be within the manufacturer's tighter tolerances.

However, the data clearly show that, as one might expect, the upper layer of the vessel, as measured at the 900-mL level,

			E	xternal Probe	's Test Temp	erature Val	ues (°C)*			
			Paddles at 25 rpm				Paddle	s at 250 rpm	250 rpm	
Vessel #	Vessel Level**	2nd	3rd	Avg. 2nd & 3rd	∆ (Avg.) ex 0.5 L	2nd	3rd	Avg. 2nd & 3rd	∆ (Avg.) ex 0.5 L	
1	0.9 L 0.5 L	36.62 36.92	36.66 37.05	36.640 36.985	-0.345	36.62 36.95	36.58 36.94	36.600 36.945	-0.345	
	Bot.	36.91	36.90	36.905	-0.080	36.90	36.89	36.895	-0.050	
2	0.9 L 0.5 L	36.46 36.96	36.50 36.95	36.480 36.955	-0.475	36.74 36.93	36.76 36.92	36.750 36.925	-0.175	
11.1.1	Bot.	36.82	36.82	36.820	-0.135	36.93	36.99	36.960	0.035	
3	0.9 L 0.5 L	36.62 37.17	36.66 37.10	36.640 37.135	-0.495	36.86 37.01	36.80 36.94	36.830 36.975	-0.145	
	Bot.	37.01	36.94	36.975	-0.160	36.99	36.96	36.975	0.000	
4	0.9 L 0.5 L	36.76 36.98	36.75 37.03	36.755 37.005	-0.255	36.74 36.97	36.74 36.96	36.740 37.965	-0.225	
	Bot.	36.93	36.97	36.955	-0.050	36.96	36.94	36.950	-0.015	
5	0.9 L 0.5 L	36.58 36.96	36.64 37.02	36.610 36.990	-0.380	36.76 37.03	36.74 37.00	36.750 37.015	-0.265	
	Bot.	37.00	36.98	36.990	-0.000	36.97	36.98	36.975	-0.030	
6	0.9 L 0.5 L	36.49 37.00	36.47 37.13	36.480 37.065	-0.585	36.65 36.95	36.72 36.94	36.675 36.945	-0.270	
	Bot.	36.97	36.92	36.945	-0.120	36.97	36.92	36.945	0.000	
7	0.9 L 0.5 L	36.50 36.97	36.52 37.03	36.510 37.000	-0.490	36.77 36.95	36.70 36.97	36.735 36.960	-0.225	
	Bot.	36.95	36.94	36.945	-0.055	36.96	36.94	36.950	-0.010	
Avg.	0.9 L 0.5 L	36.58 36.99	36.60 37.02	36.588 37.012	~ -0.42	36.78 36.97	36.72 36.95	36.756 36.961	~ -0.20	
	Bot.	36.94	36.92	36.963	~ -0.08	36.97	36.95	36.950	~ -0.01	

Table V: 25-rpm and 250-rpm covered-vessel temperature uniformity.

*Temperature measurements were made at 2-min intervals starting 2 min after the probe was positioned.
**The vessel level positions - 0.9 L, 0.5 L, and Bot. - represent placement of the measuring probe at the top, middle, and bottom of the vessel for measurements.

was slightly cooler than the bulk of the vessel's contents. At 250 rpm, the differences were all within both the manufacturer's and USP's ranges. At 25 rpm, the values still met USP's limit (36.5°C to 37.5°C) because the lowest equilibrium values observed were, within experimental uncertainty, 36.5°C. Moreover, given this result and the fact that the system converges to equilibrium temperature values within ±0.05°C of the set point, one need only adjust the system's set point

upward to 37.2°C to ensure that the temperature at the 900-mL level is within USP's allowed 36.5-37.5°C range when stirring at speeds close to 25 rpm.

Based on the data generated in this study and because the medium is continuously stirred, the dissolution of a drug unit located in the bottom of the vessel would have been taking place, on average, at 36.95°C. Furthermore, USP specifies an average temperature as opposed to a uniformity specification. Given this fact and the absence of other published data in this regard, the uniformity in each vessel serves only to establish this system's performance capabilities. Finally, the lack of a significant gradient, even when stirring at 25 rpm, between the 500-mL level and the bottom clearly established that one need not apply heat to all of the vessel's surfaces to establish a uniform, controlled temperature in the vessel's contents, at least not for paddle speeds at or above 25 rpm.

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LONG-TERM TEMPERATURE FLUCTUATION ABOUT THE SET POINT

Unlike water bath-based systems, in which the temperatures of the vessel's contents are controlled indirectly, the system in this study actively and continually monitors and seeks to control the temperature in the vessels as close to the set point as possible without significant overshoot. As such, the fluctuations seen in the system's temperature readouts are a combination of various random errors in the system's components, drifts in the temperature from the set point, and periodic additions of heat by the system as it seeks to maintain each vessel's contents at the set point. Thus, the range of values observed over time for this system represent, on average, the effective control limits for the system.

Therefore, the smallest and the largest temperature values observed in the data from the 24-h temperature-change monitoring studies served to define the long-term control limit ranges. As in the preceding studies, the midrange values were, within experimental error, all the same: ≥36.9°C (36.95 ± 0.03°C). In addition, at 250 rpm the set point control range, as defined by the lowest and the highest values seen in these studies, was 36.96 ± 0.11°C. In the 25-rpm study, as expected, the control range was larger because of lower rates of heat transfer and mixing. Based on the data from the 25-rpm study, the control range for the system was 36.97 ± 0.14 °C. In

both cases, as in all of the other studies, a set point of 37.0°C generated an effective mean temperature of ~36.95°C. Thus, setting a 37.0°C set point resulted in attaining an average vessel content temperature that is well within the limits allowed by Distek and USP. Moreover, because the system's set point increment is 0.1°C, users who wish to have the temperature of ≥37.0°C need only increase the system's set point by 0.1°C to achieve their goal. In contrast, the corresponding offset required in water bath-based dissolution systems is ~0.5°C.

COVER REMOVAL STUDIES

The only critical factor in this area that needs to be resolved is the effect, if any, that removal of the covers has on the system's ability to maintain the temperature of the medium within the vessels at the system's set point. Based on all of the previous results, we know that the system's heating circuitry will attempt to compensate for the increased heat loss caused by removing the covers. The data obtained indicated that the system compensated for the removal of the covers in a manner that left the mean shaft temperature values close to their covered value equivalents. The test readings taken near the water's surface in the vessels showed no evidence of a significant change in the temperature in the upper layer.

Based on this study - and ignoring the errors in volume and the noncompliance with USP's expectation that are introduced by removal of the covers - the effect of operating

without covers was small enough in this installation that the system continued to maintain the average temperature of the medium, as measured by the shaft probes, within both USP's and the manufacturer's tolerances (see sidebar, Note 5). However, though performed on different days and in conjunction with other studies that indicated that the system's control mean was ~36.95°C, both of these studies found a mean value of ~36.91°C. Based on these findings, removing the covers further reduced the system's control point by ~0.04°C to ~36.91°C. Thus, in addition to requiring a reliable method to measure the volume remaining at any point in time as well as installation in a low-airflow area, controlled operation without covers would require at least a 0.1°C increase in the set point to keep the measured average values at 37.0°C.

SUMMARY AND

Based on the results obtained for both the cases reported in this discussion and other performance validation studies done at the same time, the results obtained have documented the system's performance and established that the system meets USP's and the manufacturer's specifications. This compliance has been demonstrated when the system was operated at 37.0°C with 1 L of water in each vessel and with the appropriate paddles, covered vessels, and rates of rotation at 25 rpm and 250 rpm. In addition to establishing the system's conformance to

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Product News

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USP's requirements for controlled operation as well as conformance to all of the manufacturer's pertinent specifications, these studies have established the system's characteristics with respect to temperature uniformity, control point precision and accuracy, initial heating time, set point control limits, and cover removal. Appropriate studies at 25 rpm and 250 rpm have generated data that establish satisfactory performance of the system.

References

1. General Chapter <711> Dissolution, Apparatus Suitability Test, USP 23 (United States Pharmacopeial Convention, Rockville, MD), p. 1792.

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